

Research and Simulation of Table Tennis Track Prediction Based on Double Concave Round Table Tennis

Xiaoping Gou^{1, a}, Wanjun Zhang^{2, 3, 4, b, *}, Jingxuan Zhang^{2, c}, Jingyi Zhang^{3, d} and Jingyan Zhang^{4, e}

¹School of Physical Education, Longdong University, Qingyang 745000, China

²Qingyang Xinyuan Engineering Company Limited, Gansu 745000, China

³Lanzhou Industry and Equipment Company Linlimited, Lanzhou 730050, China

⁴Xi'an Jiaotong University, 710049, Shanxi China

^agouxiaoping12@sohu.com, ^bgszwj_40@163.com, ^cgszhangwj40@163.com, ^dtszhangwj40@163.com, ^e116543048@qq.com

*Corresponding author

Keywords: Double concave round table tennis bat, Kinematic model, Trajectory prediction, Simulation and analysis

Abstract: Double concave round table tennis needs to accurately predict the trajectory of fast-moving table tennis when slapping table tennis. Firstly, the kinematics model and physical model of table tennis collision used in table tennis flight trajectory prediction with biconcave round table tennis are analyzed. Secondly, the algorithm of kinematics model used in table tennis flight trajectory prediction is mainly improved. Finally, the speed feedback adjustment coefficient is not fixed but dynamic coefficient. Through MATLAB simulation, the experimental results show that the prediction effect is very good. Finally, in order to intuitively analyze and predict the trajectory and intuitively reflect the movement law of table tennis, physics will be closer to life, better applied in sports and better serve the teaching of table tennis in colleges and universities.

1. Introduction

Table tennis is known as China's "national ball", not only because table tennis players have made brilliant achievements in international competitions, but also because table tennis has a broad mass base in our country. However, table tennis is a rather difficult sport. For most table tennis enthusiasts, due to its complicated and changeable flight, table tennis often stays in a visual and perceptual understanding.

At present, table tennis racquets are reformed by various methods such as planes, inclined planes, materials, rubber plates, handles and the like. In order to improve the racket surface, the invention relates to a biconcave round table tennis racquet, in particular to a table tennis racquet with a spherical biconcave round surface processed by a lathe. The invention solves the problems that the existing table tennis bottom plate is not conducive to hitting power and pressing the cover to hit an arc ball and the like [16-25]. Lanzhou Industry and Equipment Co. Ltd, Lanzhou University of technology Zhang Wanjun studied some model identification control systems [26-33] of flexible training equipment and control methods.

In 1997, Rui Qing of Shanghai Jiaotong University and others cooperated with Professor Miyazaki of Osaka University in Japan to first theoretically study the prediction and simulation algorithm of table tennis trajectory, and proposed a table tennis trajectory prediction algorithm using local weight regression algorithm [34-38]. The advantage of this method is that it does not need to establish a dynamic model for the controlled object [39-41]. The disadvantage is that it requires a large number of effective samples, and it is difficult to distinguish whether table tennis rotates or not, and it is difficult to analyze the prediction results according to the rotation. The speed of table tennis

before rebound is very important for trajectory prediction after rebound. This paper focuses on improving the calculation method of speed before rebound in reference [42], and analyzes the feasibility of the improved algorithm by using MATLAB 6.5. At the same time, in order to intuitively analyze the predicted trajectory, a 3D simulation platform based on OpenGL is designed.

The speed of table tennis before rebound is very important for trajectory prediction after rebound. This paper focuses on improving the calculation method for calculating the speed before rebounding in reference. MATLAB 6.5 is applied to analyze the feasibility of the improved algorithm. This paper mainly improves the algorithm of kinematic model [1] used in table tennis flight trajectory prediction.

2. Double concave round table tennis bat

The technical scheme adopted by the invention for solving the technical problem is that the biconcave round table tennis bat is of biconcave streamline symmetrical design, and the bottom plate of the table tennis bat is a concave panel with thick edge and thin center. The bottom plate of the table tennis bat has an edge thickness of 6mm and the center thickness of the concave surface of the clapper is 3mm. Top view of double concave round table tennis bat, as is shown in Figure.1.

The double concave circular table tennis bat has the beneficial effects that in the process of catching and hitting balls, the concave surface reduces the failure rate of hitting balls, increases the exciting degree and the viewing power of the match, the arc spinning balls pulled out by the concave surface have higher rotating speed, thus posing greater challenges to the development of technology, achieving more stable hitting balls, easier arc drawing and cutting, more obvious tapping and cutting advantages, and realizing humanized design.

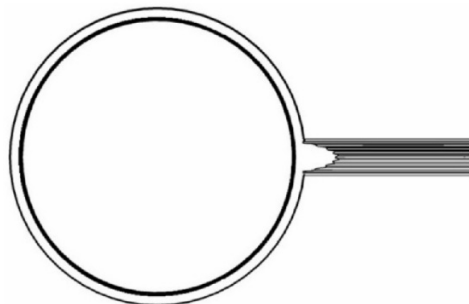
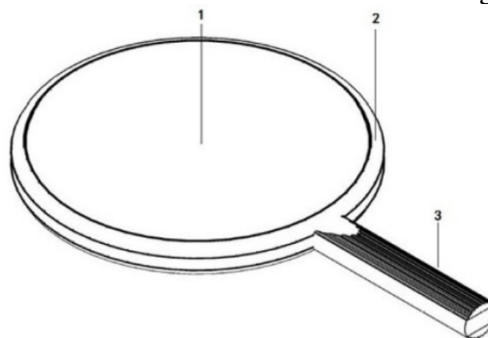


Figure 1. Top view of double concave round table tennis bat.

Diagram of 3D Decomposition of Flexible Trainer for Double Legs, as is shown in Figure.2.



1. Center of the clapper concave surface; 2. Upper edge of the clapper concave surface; 3. Groove handle.

Figure 2. Three-dimensional schematic diagram of double concave round table tennis bat.

The biconcave round table tennis bat comprises a circle center (1) of the clapper concave surface, an upper edge (2) of the clapper concave surface and a groove handle (3).

In order to overcome the defects of the existing design, the invention provides a biconcave round table tennis bat. The biconcave round table tennis bat is provided with a center 1 of the concave

surface of the clapper and an upper edge 2 of the concave surface of the clapper; and the two surfaces of the biconcave round table tennis bat are respectively stuck with positive rubber sheets and reverse rubber sheets. Groove handle 3 is provided with evenly distributed grooves on the table tennis racket handle to enhance the contact area between airflow and palm, reduce sweat absorption to the table tennis racket handle and prevent the racket from sliding from the hand.

The embodiment: the exerciser grasps the groove handle 3 with his hand, and sticks the front rubber sheet and the back rubber sheet on the two sides of the biconcave round table tennis bat respectively. In the process of catching and hitting the ball, the concave surface of the double-concave circular table tennis bat reduces the error rate of hitting the ball, increases the exciting degree of the game and the viewing force. The arc spinning ball pulled out from the concave surface has a rotating speed, which poses greater challenges to the development of technology. The ball hitting is more stable, the arc drawing becomes easier, and the tapping and cutting advantages are more obvious. The groove handle 3 is on the handle of the table tennis bat, and has evenly distributed grooves, which enhance the contact area between the air flow and the palm, reduce sweat absorption onto the table tennis handle, and prevent the racket from sliding from the hand.



Figure 3. Physical picture of double concave round table tennis bat.

3. Operational methods of hip training instruments

The prediction of the flight path of the biconcave round table tennis bat is basically divided into four steps:

(1) Trajectory tracking stage. The speed and acceleration of table tennis at each measuring point are calculated in combination with the collection time.

(2) Trajectory prediction before rebound. The physical mechanism of table tennis flight is modeled, the differential equation of table tennis flight is obtained, and the trajectory and speed of table tennis are solved.

(3) The collision between table tennis and the table. It is mainly to construct the collision model between table tennis and table tennis.

(4) Trajectory prediction after rebound. The same method is used for trajectory prediction before rebound.

4. Table Tennis Flight Model

In the process of table tennis moving in the air, it is mainly affected by two forces: gravity $G = M \cdot g$ and air resistance $F = l \cdot v^2$, where M is the mass of table tennis, g is the acceleration of gravity, and l is the air resistance coefficient. See document [1] for flight models.

(1) In the horizontal direction:

$$\begin{cases} x = \frac{M}{l} \ln \left(1 + \frac{k \cdot \mathbf{v}_{x0} \cdot t}{M} \right) + \mathbf{v}_{x0} \cdot \mathbf{x}_0 > 0 \\ x = -\frac{M}{l} \ln \left(1 - \frac{k \cdot \mathbf{v}_{x0} \cdot t}{M} \right) + \mathbf{v}_{x0} \cdot \mathbf{x}_0 < 0 \end{cases} \quad (1)$$

The Y axis in the horizontal direction has a position prediction expression consistent with the X axis.

(2) In the vertical direction:

$$\begin{cases} z = \frac{M}{k} \left| \ln \cos \left(\sqrt{\frac{l \cdot g}{M}} t \right) \right| + \mathbf{v}_{x0} \cdot \sqrt{\frac{l}{Mg}} * \\ \sin \left(\sqrt{\frac{l \cdot g}{M}} t \right) + \mathbf{v}_0 \cdot \mathbf{x}_{z0} > 0 \\ z = -\frac{M}{2k} \ln \frac{\left(1 + e^{2t \sqrt{\frac{l \cdot g}{M}}} \right)^2}{4e^{2t \sqrt{\frac{l \cdot g}{M}}}} + z_0 + \mathbf{v}_{z0} \cdot \mathbf{v}_{z0} > 0 \end{cases} \quad (2)$$

5. Collision Model between Table Tennis and Table Tennis

In order to accurately predict the trajectory of table tennis, besides establishing the precise motion equation of the flight process, it is also necessary to model the collision between table tennis and the table top and obtain a more accurate rebound model. See document [1] for the establishment of collision model.

$$\begin{cases} \mathbf{v}_{xout} = l_x \cdot \mathbf{v}_{xin} + B_x \\ \mathbf{v}_{yout} = l_y \cdot \mathbf{v}_{yin} + B_y \end{cases} \quad (3)$$

$$\mathbf{v}_{zout} = l_z \cdot \mathbf{v}_{zin} \quad (4)$$

Indicates the ratio of predicted coordinate error to time and an average velocity error, which is a dynamically corrected coefficient.

6. Experimental results and analysis

Firstly, the kinematics model and physical model of table tennis collision used in table tennis flight trajectory prediction of biconcave round table tennis are analyzed. Secondly, the algorithm of kinematics model used in table tennis flight trajectory prediction is mainly improved. Through MATLAB simulation, the experimental results show that the prediction effect is very good.

Double concave round table tennis needs to accurately predict the trajectory of fast-moving table tennis when slapping table tennis. Firstly, the kinematics model and physical model of table tennis collision used in table tennis flight trajectory prediction with biconcave round table tennis are analyzed. Secondly, the algorithm of kinematics model used in table tennis flight trajectory prediction is mainly improved. Finally, the speed feedback adjustment coefficient is not fixed but dynamic coefficient.

When $H=0.3\text{m}$ and inclination angle is $0^\circ, 60^\circ, 90^\circ, 120^\circ$ movement track of table tennis, as is shown in Figure.4, 5, 6,7and Figure.8.

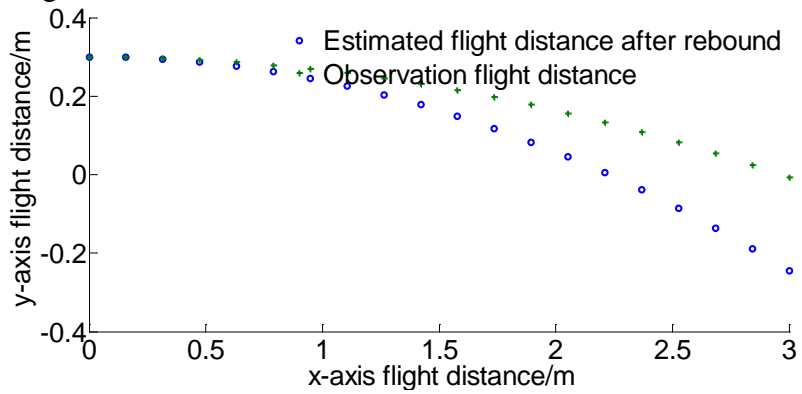


Figure 4. When $H=0.3\text{m}$ and inclination angle is 0° , movement track of table tennis.

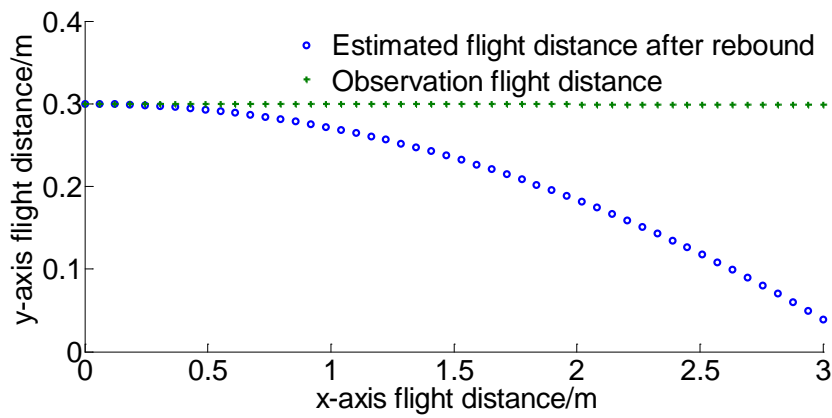


Figure 5. When $H=0.25\text{m}$ and inclination angle is 90° , movement track of table tennis.

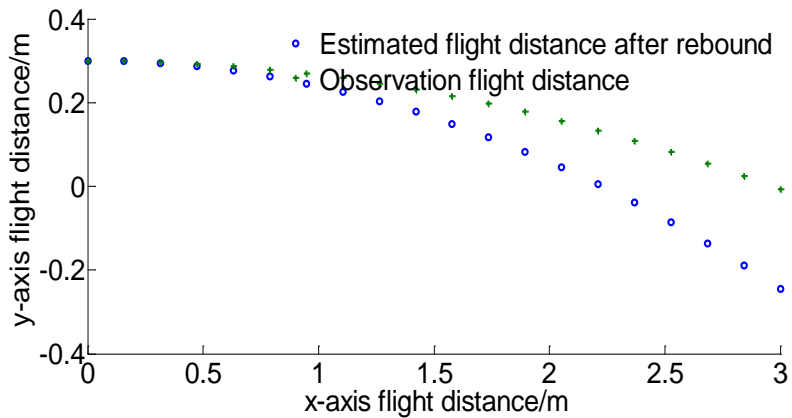


Figure 6. When $H=0.25\text{m}$ and inclination angle is 60° , movement track of table tennis.

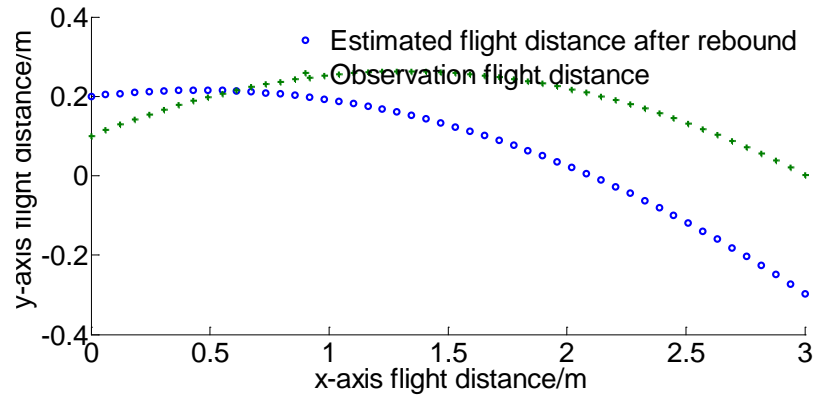


Figure 7. When $H=0.25\text{m}$ and inclination angle is 45° , movement track of table tennis.

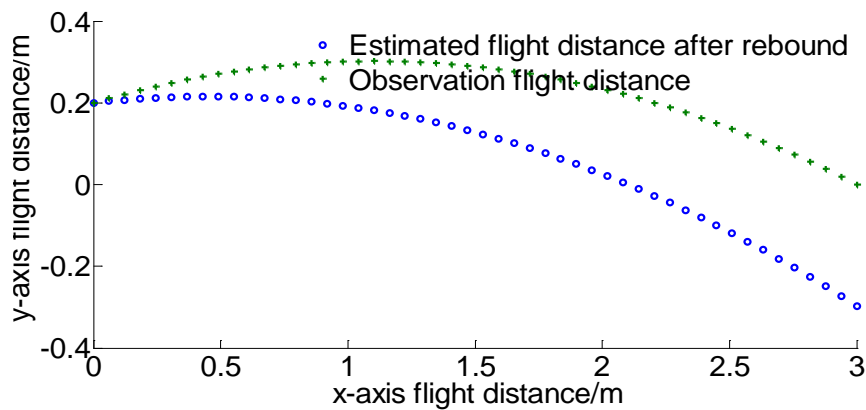


Figure 8. When $H=0.25\text{m}$ and inclination angle is 120° , movement track of table tennis.

The results show that there are significant differences between the two sides of the hip splits of young male and female athletes, but the difference in leg flexibility is not obvious, and the maximum strength of extensor muscle is relatively low.

The experimental results show that the improvement of the ratio coefficient and the improvement of the calculation of the initial speed before rebounding can more accurately predict the trajectory of table tennis and meet the requirements of playing table tennis.

7. Summary

(1) Double concave round table tennis needs to accurately predict the trajectory of fast-moving table tennis when slapping table tennis. Firstly, the kinematics model and physical model of table tennis collision used in table tennis flight trajectory prediction with biconcave round table tennis are analyzed. Secondly, the algorithm of kinematics model used in table tennis flight trajectory prediction is mainly improved. Finally, the speed feedback adjustment coefficient is not fixed but dynamic coefficient.

(2) Through MATLAB simulation, the experimental results show that the prediction effect is very good. Finally, in order to intuitively analyze the prediction trajectory and intuitively reflect the movement law of table tennis, physics will be closer to life, better applied in sports and better serve the teaching of table tennis in colleges and universities.

Acknowledgements

The authors thank the financial supports from Twelfth Five-Year Plan" of Education Science in Gansu Province (GS [2014] (GHBZ017)) and Twelfth Five-Year Plan" of Education Science in Gansu Province Planning 2016 Annual Planning Project (GS [2014] (GHBZ017)).

Author: Gou Xiaoping, male, born in 1978 with a bachelor's degree, Qingyang Science and Technology Commissioner, Patent Commissioner, and Venture Tutor of Longdong University, has obtained more than 580 authorized patents, three papers published by EI and one monograph published.

Communication author: Zhang Wanjun, male (1986-), Doctor of Engineering (Doctor of Engineering, Bachelor of Law, Bachelor of Management, etc.), Professor-level (senior) Senior Engineer, Senior Economist, Mechanical Engineer (China Institute of Mechanical Engineering, Evaluation by Examination Center of the Ministry of Education of the People's Republic of China), Senior NC Craftsman (Chinese). Evaluation by Ministry of Human Resources and Ministry of Social Security of the Republic of China), Senior Members of China Mechanical Engineering Society, Senior Members of China Agricultural Mechanical Engineering Society, Senior Members of China Agricultural Engineering Society, Senior Members of China Electrical Engineering Society, Senior Members of China Computer Society, Senior Members of China Testing Society, Members of China Development Association (Governor), Fourth Annual Invention Society of Gansu Province Members, directors and members of the board of directors; members of the Standing Council of the Committee of Experts (Standing Committee of the Committee of Experts), who are mainly engaged in the research of NC processing technology, precision manufacturing equipment technology and new energy. Up to now, more than 600 patents have been authorized for inventions and utility models, and more than 80 academic papers have been published in core and above journals, among which more than 60 papers have been retrieved in three major journals: 40 papers SCI/EI/ISTP. E-mail: gszwj_40@163.com.

References

- [1] Sun Zai, Yu Guangxin, Guo Mei. Aerodynamic principle of table tennis loop and simulation analysis of its flight path [J]. Sports Science, 2008, (4): 69.
- [2] Zhou Yuqing, Ye Zhaoning, Wu Zonghan. Calculation and analysis of air resistance in ball games [J]. Physics and Engineering, 2002, (1): 55.
- [3] Fang Jie. Study on Table Tennis Collision Using Computer Simulation Technology [J]. Journal of Tianjin Institute of Physical Education, 2003, 18 (3): 47.
- [4] He Xingsuo. Theoretical mechanics: higher dynamics [M]. Xi'an: Northwest University of Technology Press, 2003.3.
- [5] Jiang Fugao, Li Xiangchen, Xu Quanyong. Establishment and simulation of table tennis flight kinematics model [J]. Journal of Qufu Normal University, 2008, 34 (1): 104.
- [6] Ge Longqi, Ye Weijun. The laws of football rotation [J]. Physical Bulletin, 1992, (2): 7-8.
- [7] Zhu Zhaoxuan, Zhou Qizhao, Yin Jinsheng. Theoretical Mechanics (First Volume) [M]. Beijing: Peking University Press, 1982. 258.
- [8] Zhao Kaihua, Luo Weiyin. Mechanics [M]. Beijing: Higher Education Press, 1996.240-242.
- [9] Liu Dawei. Discussion on Abnormal Trajectory of Sphere [J]. University Physics, 1987, (1): 43-45.
- [10] Zhang Wanjun, Zhang Feng, Zhang Jingxuan, et al. Research on the vector control system based on the difference frequency of wind turbine generator. [J]. Materials Science and Engineering, 2018, 8, Vol. 394. 042020: 1-9.
- [11] Zhang Wanjun, Zhang Feng, Zhang Jingxuan, et al. Curved Measurement Theory of Honing Pneumatic Measurement System and Optimization of Measurement Parameters. [J]. Journal of Physics, 2018, 8, Vol. 1064. 012028: 1-14.

- [12] ZhangWanJun, ZhangFeng, ZhangJingxuan, et, al. Flow field analysis and parameter optimization of main and measured nozzles of differential pressure type gas momentum instrument based on CFD. [J]. Journal of Physics, 2018, 8, Vol. 1064. 012028: 1-12.
- [13] Zhang WanJun, Zhang Feng, Zhang Wanliang, et al. Fuzzy Control of Wind Turbine Based on Directional Power Conversion. [J]. Electric Power Construction, 2014, 10, 35 (10): 13-16.
- [14] Zhang WanJun, Zhang Feng, Zhang Guohua. Research on an algorithm of adaptive interpolation for NURBS curve. [J]. Applied Mechanics and Materials, Vol. 687-691, pp.1600-1603, December 2014.
- [15] Zhang Wan-Jun, Zhang Feng, Zhang Guohua. Research on modification algorithm of Cubic B-spline curve interpolation technology. [J]. Applied Mechanics and Materials, Vol. 687-691, pp.1596-1599, December 2014.
- [16] Zhang Wan-Jun, Zhang Feng, Zhang Wan-liang. Research on high-grade CNC machines tools CNC system for B-Spline curve method of High-speed real-time interpolation arithmetic [J]. Chinese Journal of Manufacturing Technology & Machine Tool, 8 (8), pp.172-176, August 2015.
- [17] Zhang Wan-Jun, Zhang Feng, Zhang Guo-hua. Research on modification algorithm of Cubic B-spline curve interpolation technology. [J]. Applied Mechanics and Materials, Vol. 687-691, pp.1596-1599, December 2014.
- [18] Zhang Wan-Jun, Zhang Feng, Zhang Wan-Liang. Research on a NURBS curve of timing / interrupt interpolation algorithm for CNC system [J]. Chinese Journal of Manufacturing Technology & Machine Tool, 4 (4), pp.183-187, April 2015.
- [19] Zhang Wan-Jun, Hu Chi-Bing, Zhang Feng, et al. Honing machine motion control card three B spline curve method of interpolation arithmetic for CNC system [J]. Chinese Journal of Manufacturing Technology & Machine Tool, 8 (8), pp.40-43, August 2012.
- [20] Zhang Wan-Jun, HU Chi-bing, WU Zai-xin, et, al. Research on modification algorithm of Three B Spline curve interpolation technology [J]. Chinese Journal of Manufacturing Technology & Machine Tool, 2 pp.141-143, February 2013.
- [21] Zhang WanJun, Zhang, Gao Shanping, Zhang Sujia. Modification algorithm of Cubic B-spline curve interpolation. [J]. Advances in Engineering Research, 2016, 12, Vol. 83. 513-518.
- [22] Zhang WanJun, Zhang, Gao Shanping, Zhang Sujia. Modification algorithm of NURBS curve interpolation. [J]. 2016 4th International conference on Machinery, materials and Information Technology Applications, 2016, 12, Vol.71. 507-512.
- [23] Zhang WanJun, Zhang, Gao Shanping, Zhang Sujia. Modification algorithm of Cubic B-spline curve interpolation. [J]. 2016 4th International conference on Machinery, materials and Information Technology Applications, 2016, 12, Vol.71. 513-518.
- [24] ZhangWanJun, ZhangFeng, ZhangJingxuan, et, al. Modeling and identification of system model parameters based on information granularity method. [C] // Proceedings of the IEEE International Conference on Computers, Signals and systems. Dalian, 2018: 114–118.
- [25] ZhangWanJun, ZhangFeng, ZhangJingxuan, et, al. Optimization of identification structure parameters based on recursive maximum likelihood iteration. [C] // Proceedings of the IEEE International Conference on Computers, Signals and systems. Dalian, 2018: 119–124.
- [26] ZhangWanJun, ZhangFeng, ZhangJingxuan, et, al. Parameter optimization and model identification of identification model control based on improved generalized predictive control. [C] // Proceedings of the IEEE International Conference on Computers, Signals and systems. Dalian, 2018: 125–129.

- [27] ZhangWanJun, ZhangFeng, ZhangJingxuan, et, al. Study on System Recognition Method for Newton-Raphson Iterations. [C]// Proceedings of the IEEE International Conference on Computers, Signals and systems. Dalian, 2018: 130–135.
- [28] Zhang WanJun, Zhang, Gao Shanping, Zhang Sujia. A improved algorithm of three B-spline curve interpolation and simulation. [J]. Advances in Materials, materials, Machinery, Electronics I, 2017, 2, Vol. 1820. 080004-1- 080004-6.
- [29] Liu Xin. Research on the Kinematic Characteristics of the Last Two Steps of Throwing and Final Effort of Chinese Excellent Female Javelin Athletes. [P]. Xi'an: Xi'an Physical Education University, 2017.
- [30] Gou Xiaoping; Xiong Zhenqiang; Tian Huijun; Turbo Hip Reduction Hip Joint Trainer with Hip Turbine Opening Backward on the Stand with Two Legs Separated on the Stand [P]. China Patent: CN102600577A, 2012-07-25.
- [31] Gou Xiaoping; Xiong Zhenqiang; Tian Huijun; Turbo Hip Reduction Hip Joint Trainer with Hip Turbine Opening Backward on the Stand with Two Legs Separated on the Stand [P]. China Patent: CN202538261U, 2012-11-21.
- [32] Gou Xiaoping; Xiong Zhenqiang; Invention and Application of Flexible Hip Joint Training Instruments [J] Sports Articles and Science and Technology. 2012, (18).
- [33] Yuan Mingyu; Gou Xiaoping; Xiong Zhenqiang. Arm and wrist strength trainer [P]. Chinese patent: CN102908748A, 2013-02-06.
- [34] Huang Caihua, Gao Songling. The influence of PNF stretching and static stretching on female college students'physical flexibility [J]. Journal of Fujian Normal University (Natural Science Edition). 2004 (03).
- [35] Zhang WanJun, ZhangFeng, Zhang Jingxuan, et, al. Application of digital image processing technology in polyaniline deposition on the surface of carbonyl iron powder [J]. Earth and Environmental Science, 2018, 12, Vol. 252: 491-500.
- [36] Zhang WanJun, ZhangFeng, Zhang Jingxuan, et, al. Effect of space stabilizer on in-situ deposition of polyaniline on carbonyl iron powder [J]. Earth and Environmental Science, 2018, 12, Vol. 252: 501-509.
- [37] Zhang WanJun,ZhangFeng,Zhang Jingxuan,et,al. One-dimensional mathematical model of coal combustion in furnace and its simulation [J]. Earth and Environmental Science, 2018, 12, Vol. 252: 1822-1833.
- [38] Zhang WanJun, ZhangFeng, Zhang Jingxuan, et, al. Research on Fuzzy Control Based on Directional Power Conversion of Wind Generator [J]. Earth and Environmental Science, 2018, 12, Vol. 252: 1912-1923.
- [39] Gou xiaoping, Zhang WanJun, ZhangFeng, et, al. Study on the Structure Design and Feasibility Analysis of Apple Inhaled Box Bags Based on Hailproof [J]. Earth and Environmental Science, 2018, 12, Vol. 252: 3826-3837.
- [40] Zhang Wan Jun, Zhang Feng, Zhang Guohua. Research on modification algorithm of Cubic B-spline curve interpolation technology. [J]. Applied Mechanics and Materials, Vol. 687-691, pp.1596-1599, December 2014.
- [41] Zhang WanJun, Zhang Feng, Zhang Wan-liang. Research on high-grade CNC machines tools CNC system for B-Spline curve method of High-speed real-time interpolation arithmetic [J]. Chinese Journal of Manufacturing Technology & Machine Tool, 8 (8), pp.172-176, August 2015.

[42] ZhangWanJun, ZhangFeng, ZhangJingxuan, et, al. Research on cross coupled contour error compensation technology in CNC multi axis linkage of Machine tool [J]. Chinese Journal of Manufacturing Technology & Machine Tool, June. pp. 154-159, 2018.

[43] ZhangWanJun, ZhangFeng, ZhangJingxuan, et, al. Cross coupled contour error compensation technology. [J]. Materials Science and Engineering, 2018, 8, Vol. 394. 032031: 1-5.